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Abstract of the Disclosure

A floor working machine includes a U-turn control unit for causing a self-propelled vehicle body to make a U-turn automatically to adjust the working implement to a work line adjacent a work line treated before the U-turn, a spin turn control unit for causing the self-propelled vehicle body to make a spin turn automatically to adjust the working implement to a work line adjacent a work line treated before the spin turn, and a running control unit for automatically controlling the U-turn control unit and the spin turn control unit in response to input signals for causing the self-propelled vehicle body to make selectively a U-turn under control of the U-turn control unit and a spin turn under control of the spin turn control unit.

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